Learning from the dual parameterization Approximate inference and learning in Gaussian process models

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Joint work...



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Outline

Gaussian process model

Laplace approximation

Variational inference

Hyperparameter learning

Sparse approximation

Sequential learning

prior:
$$p(f(\cdot)) = \mathcal{GP}(\mu(\cdot), \kappa(\cdot, \cdot))$$

likelihood: $p(\mathbf{y} | \mathbf{f}) = \prod_{i=1}^{n} p(y_i | f_i), e.g.$ Bernoulli for classification
posterior: $p(f(\cdot) | \mathbf{y}) \propto p(\mathbf{y} | \mathbf{f}) p(f(\cdot))$ intractable
 $\approx q(f(\cdot))$ approximate inference

Approximate inference for non-conjugate likelihood models

- MCMC (sampling) methods (accurate but generally heavy)
- Laplace approximation (LA) (fast and simple)
- Expectation propagation (EP) (efficient but tricky)
- Variational methods (VB/VI) (popular but not problem-free)



GP classification with a Bernoulli likelihood

Gaussian approximate posterior

$$p(\mathbf{f} \mid \mathbf{y}) pprox q(\mathbf{f})$$

 $q(\mathbf{f}) = \mathrm{N}(\mathbf{f}; \mathbf{m}, \mathsf{S})$

How to find **m** and S?

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Laplace approximation

$$p(\mathbf{f} \mid \mathbf{y}) \approx q(\mathbf{f})$$

$$q(\mathbf{f}) = N(\mathbf{f}; \mathbf{m}, S)$$
How to find \mathbf{m} and S ?
$$(\mathbf{f} \mid \mathbf{y}) = N(\mathbf{f}; \mathbf{m}, S)$$

$$(\mathbf{f} \mid \mathbf{y})$$

$$(\mathbf{f} \mid \mathbf{y})$$

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Laplace approximation, mean parameter **m**

posterior:

 $ho(\mathbf{f} \,|\, \mathbf{y}) \propto
ho(\mathbf{y} \,|\, \mathbf{f}) \,
ho(\mathbf{f})$

Laplace objective:

$$\mathcal{L}_{Lap} = \log p(\mathbf{y} \,|\, \mathbf{f}) + \log p(\mathbf{f})$$

mode of posterior:

$$\mathbf{m} = \mathbf{f}^* = rg\max_{\mathbf{f}} \mathcal{L}_{\mathsf{Lap}}(\mathbf{f})$$

(log-concave likelihoods: convex optimization, unique global maximum)
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We can find a different (dual) parameterization!

Stationary point of $\mathcal{L}_{Lap} = \log p(\mathbf{y} | \mathbf{f}) + \log p(\mathbf{f})$

At the optimum:

 $\log p(\mathbf{f}) = -\frac{1}{2}\mathbf{f}^{\mathsf{T}}\mathsf{K}^{-1}\mathbf{f} + \text{const.}$

$$0 = \nabla_{f} \mathcal{L}_{Lap} \Big|_{f=f^{*}}$$

$$= \underbrace{\nabla_{f} \log p(\mathbf{y} | \mathbf{f})}_{\text{likelihood term}} \Big|_{f=f^{*}} + \underbrace{\nabla_{f} \log p(\mathbf{f})}_{\text{prior term}} \Big|_{f=f^{*}}$$

$$= \underbrace{\nabla_{f} \log p(\mathbf{y} | \mathbf{f})}_{=:\alpha(f^{*})} - K^{-1} \mathbf{f} \Big|_{f=f^{*}}$$

$$= \alpha^{*} - K^{-1} \mathbf{f}^{*} \quad \Leftrightarrow \quad \mathbf{f}^{*} = K \alpha^{*}$$

 \Rightarrow mode can equivalently be parameterized through the derivatives of the likelihood \Rightarrow dual parameterization

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What about the covariance S?

Laplace approximation: 2nd-order Taylor approximation to log posterior.

precision
$$S^{-1} = -\nabla_f^2 \mathcal{L}_{Lap} |_{f=f^*}$$

Hessian of negative log posterior, $-\mathcal{L}_{Lap} = -\log p(\mathbf{y} | \mathbf{f}) - \log p(\mathbf{f})$:

$$-\nabla_{f}^{2}\mathcal{L}_{Lap}\big|_{f=f^{*}} = \underbrace{-\nabla_{f}^{2}\log p(\mathbf{y} \mid \mathbf{f})\big|_{f=f^{*}}}_{=:W} + \mathsf{K}^{-1}$$

For factorizing likelihood, $p(\mathbf{y} | \mathbf{f}) = \prod_{i=1}^{n} p(y_i | f_i)$: $W = -\nabla_{\mathbf{f}}^2 \log p(\mathbf{y} | \mathbf{f}) \Big|_{\mathbf{f} = \mathbf{f}^*} = \operatorname{diag}(\boldsymbol{\beta}), \qquad \beta_i = -\frac{\partial^2}{\partial f_i^2} \log p(y_i | f_i)$

$$\Rightarrow S_{Lap} = (W + K^{-1})^{-1}$$

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Laplace approximation is local



Instead of point estimate (and post-hoc uncertainty), we may prefer optimizing over a whole posterior distribution directly \Rightarrow variational inference (VI)

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Dual parameterization of VI



From Laplace to VI

Stationary point

$$q^*(\mathbf{f}) = \arg \max_{q} \mathcal{L}_{\mathsf{ELBO}}[q] \qquad \text{for } q(\mathbf{f}) = \mathrm{N}(\mathbf{m}, \mathsf{S})$$

Now two stationary point equations:

 $0 = \nabla_{\mathbf{m}} \mathcal{L}_{\mathsf{ELBO}}$ $0 = \nabla_{\mathsf{S}} \mathcal{L}_{\mathsf{ELBO}}$

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Equation for mean \boldsymbol{m}

$$\nabla_{\mathsf{m}} \mathcal{L}_{\mathsf{ELBO}}[q(\mathbf{f})] = \nabla_{\mathsf{m}} \mathbb{E}_{q(\mathbf{f})}[\log p(\mathbf{y} | \mathbf{f})] - \nabla_{\mathsf{m}} \operatorname{KL}[q(\mathbf{f}) || p(\mathbf{f})]$$
$$\operatorname{KL}[q(\mathbf{f}) || p(\mathbf{f})] = \operatorname{KL}[\operatorname{N}(\mathbf{m}, \mathsf{S}) || \operatorname{N}(\mathbf{0}, \mathsf{K})] = \frac{1}{2} \left(\operatorname{Tr}(\mathsf{K}^{-1}\mathsf{S}) - n + \mathbf{m}^{\mathsf{T}}\mathsf{K}^{-1}\mathbf{m} + \log \frac{\det \mathsf{K}}{\det \mathsf{S}} \right)$$
$$\nabla_{\mathsf{m}} \operatorname{KL}[q(\mathbf{f}) || p(\mathbf{f})] = \mathsf{K}^{-1}\mathbf{m}$$

$$\nabla_{\mathsf{m}} \mathbb{E}_{q(\mathsf{f})}[\log p(\mathbf{y} \mid \mathbf{f})] = \mathbb{E}_{q(\mathsf{f})}[\nabla_{\mathsf{f}} \log p(\mathbf{y} \mid \mathbf{f})] =: \boldsymbol{\alpha}$$
Bonnet's theorem

At optimum:

$$0 = \boldsymbol{\alpha}^* - \mathsf{K}^{-1} \mathbf{m}^* \qquad \Leftrightarrow \qquad \mathbf{m}^* = \mathsf{K} \boldsymbol{\alpha}^*$$

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Equation for covariance S

more complicated...

Reparameterizations

$$q(\mathbf{f}) = N(\mathbf{m}, S)$$

- mean-covariance: $\xi = (\mathbf{m}, S)$ (and whitened reparameterization)
- natural parameters: $\eta = (S^{-1}\mathbf{m}, -\frac{1}{2}S^{-1})$
- expectation parameters: $\mu = (\mathbf{m}, \mathbf{m}\mathbf{m}^{\mathsf{T}} + \mathsf{S})$

Lagrangian dual

$$\mathcal{L}_{\mathsf{ELBO}}[q(\mathbf{f})] = \mathbb{E}_{q(\mathbf{f})} \log p(\mathbf{y} | \mathbf{f}) - \mathrm{KL}[q(\mathbf{f}) \| p(\mathbf{f})]$$

Introducing local $\tilde{\mu}$ and moment-matching constraint:

$$\mathcal{L}_{\text{Lagrange}}(\tilde{\mu}, \mu, \lambda) = \sum_{i=1}^{n} \mathbb{E}_{\tilde{q}_{i}}(f_{i}; \tilde{\mu}_{i}) [\log p(y_{i} \mid f_{i})] - \sum_{i=1}^{n} \langle \lambda_{i}, \tilde{\mu}_{i} - \mu_{i} \rangle - \text{KL} \big[q(\mathbf{f}; \mu) \| p(\mathbf{f}) \big]$$

Stationary point:

 $q^*(\mathbf{f})$ has natural parameters $\eta^*_q = \eta_{
ho} + \lambda^*$

 $\eta_a - \eta_a$

$$\begin{array}{lll} 0 = \nabla_{\lambda} \mathcal{L}_{\text{Lagrange}} & \Rightarrow & \mu^{*} = \tilde{\mu}^{*} \\ 0 = \nabla_{\tilde{\mu}} \mathcal{L}_{\text{Lagrange}} & \Rightarrow & \lambda_{i}^{*} = \nabla_{\mu_{i}} \mathbb{E}_{q^{*}(f_{i})}[\log p(y_{i} \mid f_{i})] \\ 0 = \nabla_{\mu} \mathcal{L}_{\text{Lagrange}} & \Rightarrow & \lambda^{*} = \underbrace{\nabla_{\mu} \operatorname{KL}[q(\mathbf{f}; \mu^{*}) \| p(\mathbf{f})]}_{\lambda^{*}} \end{array}$$

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Optimal $q^*(\mathbf{f})$

Optimal
$$q^*(\mathbf{f})$$
 has natural parameters $\eta_q^* = \eta_p + \lambda^*$
Prior $p(\mathbf{f})$ has natural parameters $\eta_p = (0, -\frac{1}{2}\mathsf{K}^{-1})$

In mean-covariance parameterization:

$$\mathbf{m}^* = \mathsf{K} \boldsymbol{\alpha}^* \qquad \qquad \boldsymbol{\alpha}^* = \mathbb{E}_{q^*(f)} [\nabla_f \log p(\mathbf{y} \mid \mathbf{f})]$$
$$(\mathsf{S}^*)^{-1} = \mathsf{K}^{-1} + \boldsymbol{\beta}^* \qquad \qquad \boldsymbol{\beta}^* = \mathbb{E}_{q^*(f)} [-\nabla_f^2 \log p(\mathbf{y} \mid \mathbf{f})]$$

 \Rightarrow optimal Gaussian approximate posterior for factorizing likelihoods:

$$q^*(\mathbf{f}) = \frac{1}{Z}p(\mathbf{f})\prod_{i=1}^n t_i(f_i)$$

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Optimal posterior decomposition



Natural gradient updates:

$$\lambda^{k+1} = (1 - \rho)\lambda^{k} + \rho \nabla_{\mu} \mathbb{E}_{q(f)}[\log p(\mathbf{y} | \mathbf{f})]$$

$$learning rate$$

cheap: same cost as standard gradient descent, no dense Hessian required!

Learning hyperparameters θ



- ▶ $p(\theta \mid D)$: e.g. MCMC
- ▶ point estimate θ^*
 - maximum likelihood: $\theta^* = \arg \max_{\theta} p(\mathcal{D} | \theta)$

Marginal likelihood

$$\log p(\mathcal{D} | \theta) = \log \int p(\mathcal{D} | \mathbf{f}) p(\mathbf{f} | \theta) d\mathbf{f}$$

Laplace:
$$\log p(\mathbf{y} | \theta) = \log \int \exp(\mathcal{L}_{\text{Lap}}(\mathbf{f})) d\mathbf{f}$$
$$\approx \mathcal{L}_{\text{Lap}}(\mathbf{f}^*) - \frac{1}{2} \log \det S_{\text{Lap}} + \text{const.}$$

VI:
$$\log p(\mathbf{y} | \theta) \ge \mathcal{L}_{\text{ELBO}}[q^*]$$
EP:
$$\log p(\mathbf{y} | \theta) \approx \mathcal{L}_{\text{EP}}[q^*]$$
$$= \log \int p(\mathbf{f}) \prod_{i=1}^{n} t(f_i) d\mathbf{f}$$

Same form as dual parameterization!

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Marginal likelihood estimation



Variational Expectation–Maximization

$$\begin{array}{ll} \text{E-step (inference):} & \boldsymbol{\lambda}^{(k+1)} \leftarrow \arg\max_{\boldsymbol{\lambda}} \mathcal{L}_{\mathrm{E}}(\boldsymbol{\lambda}, \boldsymbol{\theta}^{(k)}) \\ \text{M-step (learning):} & \boldsymbol{\theta}^{(k+1)} \leftarrow \arg\max_{\boldsymbol{\theta}} \mathcal{L}_{\mathrm{M}}(\boldsymbol{\lambda}^{(k+1)}, \boldsymbol{\theta}) \end{array} \end{array}$$

$$\mathcal{L}_{\rm E} \equiv \mathcal{L}_{\sf ELBO}$$
 $\mathcal{L}_{\rm M} \equiv \mathcal{L}_{\sf EP}$

	(n, d)	LA	EP	VI	Ours	МСМС
trains	(10, 30)	-0.702±0.025	-0.698 ± 0.033	-0.702 ± 0.037	-0.691 ± 0.046	-0.692 ± 0.025
balloons	(16, 5)	-0.660 ± 0.125	-0.650 ± 0.128	-0.649 ± 0.185	-0.607 ± 0.227	-0.684 ± 0.076
fertility	(100, 10)	-0.388 ± 0.122	-0.384 ± 0.149	-0.393 ± 0.136	-0.397 ± 0.139	-0.382 ± 0.126
pittsburg-bridges-T-OR-D	(102, 8)	-0.299 ± 0.081	-0.321 ± 0.108	-0.290 ± 0.110	-0.293 ± 0.116	-0.306 ± 0.115
acute-nephritis	(120, 7)	-0.203 ± 0.012	-0.046 ± 0.007	-0.007 ± 0.002	-0.005 ± 0.002	-0.005 ± 0.002
acute-inflammation	(120, 7)	$-0.184{\pm}0.018$	-0.052 ± 0.007	-0.007 ± 0.002	-0.007 ± 0.002	-0.007 ± 0.003
echocardiogram	(131, 11)	-0.424 ± 0.093	-0.418 ± 0.095	-0.425 ± 0.110	-0.428 ± 0.112	-0.437 ± 0.127
hepatitis	(155, 20)	-0.370 ± 0.071	-0.372 ± 0.072	-0.364 ± 0.090	-0.367 ± 0.094	-0.369 ± 0.091
parkinsons	(195, 23)	-0.260 ± 0.031	-0.295 ± 0.056	-0.160 ± 0.050	-0.141 ± 0.046	-0.145 ± 0.044
breast-cancer-wisc-prog	(198, 34)	-0.458 ± 0.075	-0.473 ± 0.091	-0.457 ± 0.085	-0.460 ± 0.088	-0.464 ± 0.085
spect	(265, 23)	-0.593 ± 0.049	-0.590 ± 0.055	-0.594 ± 0.054	-0.595 ± 0.054	-0.596 ± 0.051
statlog-heart	(270, 14)	-0.395 ± 0.064	$-0.389 {\pm} 0.061$	-0.396 ± 0.071	-0.397 ± 0.071	-0.397 ± 0.070
haberman-survival	(306, 4)	-0.530 ± 0.053	-0.532 ± 0.059	-0.531 ± 0.055	-0.531 ± 0.055	-0.520 ± 0.063
ionosphere	(351, 34)	-0.224 ± 0.042	-0.230 ± 0.042	-0.170 ± 0.048	-0.170 ± 0.055	-0.179 ± 0.058
horse-colic	(368, 26)	-0.463 ± 0.059	-0.452 ± 0.057	-0.467 ± 0.072	-0.473 ± 0.082	-0.469 ± 0.079
congressional-voting	(435, 17)	-0.640 ± 0.028	-0.639 ± 0.030	-0.641 ± 0.030	-0.642 ± 0.029	-0.644 ± 0.027
cylinder-bands	(512, 36)	-0.488 ± 0.038	-0.500 ± 0.041	-0.465 ± 0.049	-0.451 ± 0.052	-0.451 ± 0.049
breast-cancer-wisc-diag	(569, 31)	-0.085 ± 0.026	$-0.140{\pm}0.020$	-0.077 ± 0.044	-0.075 ± 0.045	-0.076 ± 0.043
ilpd-indian-liver	(583, 10)	-0.513 ± 0.040	$-0.520{\pm}0.041$	-0.512 ± 0.043	-0.512 ± 0.043	-0.512 ± 0.042
monks-2	(601, 7)	-0.491 ± 0.025	-0.512 ± 0.028	-0.464 ± 0.031	-0.442 ± 0.033	-0.437 ± 0.032
statlog-australian-credit	(690, 15)	-0.630 ± 0.026	-0.639 ± 0.036	-0.630 ± 0.026	-0.630 ± 0.026	-0.630 ± 0.025
credit-approval	(690, 16)	-0.342 ± 0.047	-0.342 ± 0.050	-0.341 ± 0.052	-0.342 ± 0.052	-0.341 ± 0.052
breast-cancer-wisc	(699, 10)	-0.094 ± 0.025	-0.093 ± 0.023	-0.093 ± 0.029	-0.093 ± 0.029	-0.093 ± 0.029
blood	(748, 5)	-0.478 ± 0.039	-0.479 ± 0.040	-0.478 ± 0.039	-0.478 ± 0.039	-0.478 ± 0.039
pima	(768, 9)	-0.474 ± 0.033	-0.476 ± 0.038	-0.474 ± 0.035	-0.474 ± 0.035	-0.474 ± 0.035
mammographic	(961, 6)	-0.407 ± 0.038	-0.407 ± 0.040	-0.408 ± 0.040	-0.408 ± 0.040	-0.408 ± 0.040
statlog-german-credit	(1000, 25)	-0.491 ± 0.030	$-0.491{\pm}0.032$	$-0.492{\pm}0.032$	$-0.492{\pm}0.032$	$-0.492{\pm}0.032$
Bold Count		14	13	13	16	/

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Relative accuracy (compared to best method on each data set)



Optimization issues...



What about big data?

Sparse approximation using $\mathbf{u} = f(Z)$:

$$q_{\mathsf{u}}(f(\cdot);\boldsymbol{\xi}_{\mathsf{u}},\boldsymbol{\theta}) = \int p(f(\cdot) \mid \mathbf{u};\boldsymbol{\theta}) q(\mathbf{u};\boldsymbol{\xi}_{\mathsf{u}}) \,\mathrm{d}\mathbf{u},$$

Dual parameters:

$$\hat{\alpha}_i = \mathbb{E}_{q_u(f_i)}[\nabla_{f_i} \log p(y_i \mid f_i)] \qquad \qquad \hat{\beta}_i = \mathbb{E}_{q_u(f_i)}[-\nabla_{f_i}^2 \log p(y_i \mid f_i)]$$

Projection onto sparse inducing points:

$$\boldsymbol{\alpha}_{u} = \sum_{i=1}^{n} \mathbf{k}_{z_{i}} \hat{\alpha}_{i} \qquad \mathbf{B}_{u} = \sum_{i=1}^{n} \mathbf{k}_{z_{i}} \hat{\beta}_{i} \mathbf{k}_{z_{i}}^{\mathsf{T}}$$

$$\underbrace{\mathbf{k}_{z_{i}} \hat{\alpha}_{i}}_{\text{vector evaluated from kernel } \kappa(\mathbf{x}_{i}, \mathbf{z}_{j})}_{\text{vector evaluated from kernel } \kappa(\mathbf{x}_{i}, \mathbf{z}_{j})}$$

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Sparse marginal likelihood approximations



Additive structure of dual parameterization in sequential learning

$$\hat{\alpha}_{i} = \mathbb{E}_{q_{u}(f_{i})} [\nabla_{f_{i}} \log p(y_{i} \mid f_{i})] \qquad \hat{\beta}_{i} = \mathbb{E}_{q_{u}(f_{i})} [-\nabla_{f_{i}}^{2} \log p(y_{i} \mid f_{i})]$$
$$\boldsymbol{\alpha}_{u} = \sum_{i=1}^{n} \mathbf{k}_{z_{i}} \hat{\alpha}_{i} \qquad \mathbf{B}_{u} = \sum_{i=1}^{n} \mathbf{k}_{z_{i}} \hat{\beta}_{i} \mathbf{k}_{z_{i}}^{\mathsf{T}}$$

$$\mathcal{L}_{\text{batch}}(\mathbf{m}, \mathsf{S} \mid \mathcal{D}) = \sum_{i \in \mathcal{D}} \mathbb{E}_{q_{\mathsf{u}}(f_i)}[\log p(y_i \mid f_i)] - \mathrm{KL}[q_{\mathsf{u}}(\mathbf{u}) \parallel p_{\theta}(\mathbf{u})]$$
$$\mathcal{L}_{\text{batch}}(\mathbf{m}, \mathsf{S} \mid \mathcal{D}_{\text{odd}} \cup \mathcal{D}_{\text{new}}) = \sum_{i \in \mathcal{D}_{\text{odd}} \cup \mathcal{D}_{\text{new}}} \mathbb{E}_{q_{\mathsf{u}}(f_i)}[\log p(y_i \mid f_i)] - \mathrm{KL}[q_{\mathsf{u}}(\mathbf{u}) \parallel p_{\theta}(\mathbf{u})]$$

$$\boldsymbol{\alpha}_{u} = \boldsymbol{\alpha}_{u}^{old} + \boldsymbol{\alpha}_{u}^{new}$$
 and $\mathbf{B}_{u} = \mathbf{B}_{u}^{old} + \mathbf{B}_{u}^{new}$

 \blacktriangleright natural gradient descent on new batch to find $\pmb{\alpha}_u^{new}$ and \pmb{B}_u^{new}

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Continual learning



Bayesian optimization with fantasizing



Learning from the dual parameterization

- ▶ Dual parameters: derivatives of log likelihood ⇔ sensitivities w.r.t. data points
- + Cheap natural gradient updates
- + EP-like objective for hyperparameter learning
- + Good parameterization for sequential learning

Find out more:

- Improving Hyperparameter Learning under Approximate Inference in Gaussian Process Models. Li, John, & Solin; ICML 2023. (arXiv:2306.04201)
- Memory-Based Dual Gaussian Processes for Sequential Learning.
 Chang, Verma, John, Solin, & Khan; ICML 2023.
 (arXiv:2306.03566)
- b *Dual parameterization for dummies* (in preparation, coming to an arXiv near you)

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